

# **NASA Experience with UAS Science Applications**

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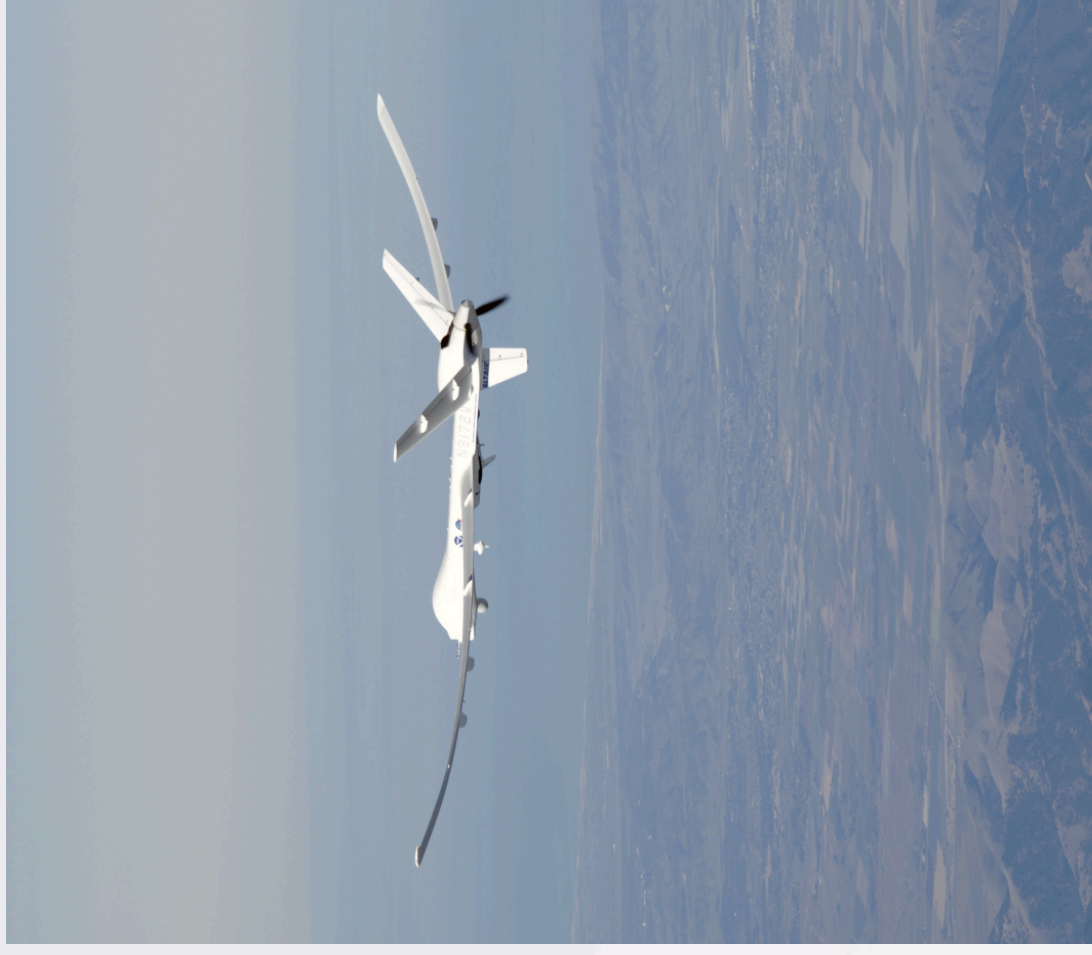
NASA Dryden Flight Research Center  
Edwards, CA

American Society for Photogrammetry & Remote Sensing  
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# Agenda

- Background
- Science demonstration missions
  - USCG Alaska
  - NOAA Channel Islands
  - Western States Fire
  - Esperanza Fire
- Current Status of NASA Dryden UAS Science Platforms
- Summary



# Background

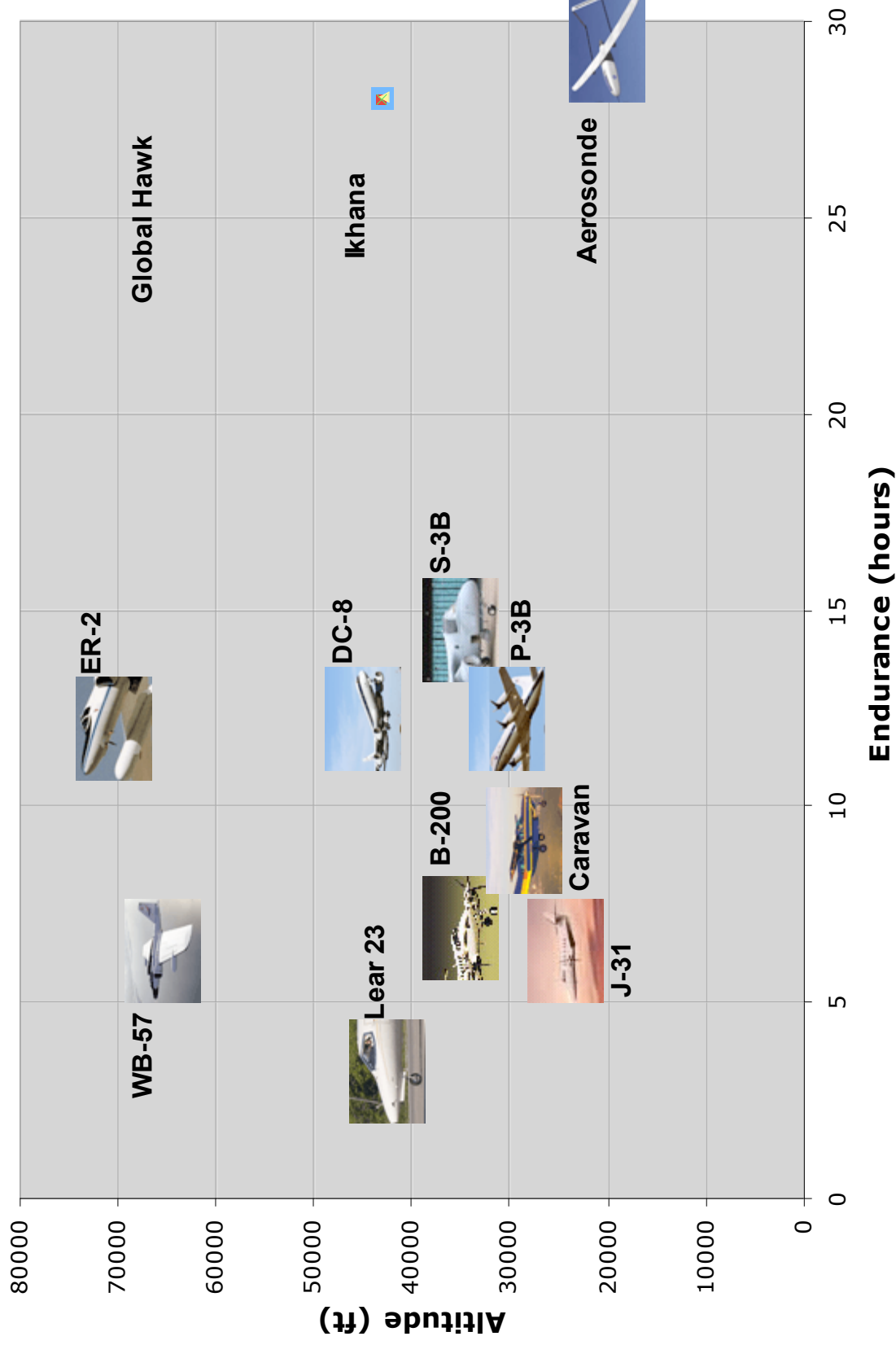
- NASA Sub-Orbital Science Program
  - Objectives
    - ♣ Development of space-based sensors
    - ♣ Satellite calibration/validation
    - ♣ Ephemeral phenomena
    - ♣ Atmosphere/near-space in-situ observations
    - ♣ Improve Earth process models
  - Aircraft Platforms
    - ♣ Traditional: ER-2's, DC-8, WB-57's, others

♣ **New Technology: UAS's**

- Why Unmanned Aerial Systems (UAS's) for Science Missions ?
  - Unique capabilities
    - ♣ duration
    - ♣ range
  - Operations in hazardous locations
    - ♣ extended polar missions
    - ♣ volcanic plumes, hurricane
  - Implications for the future of environmental monitoring & response missions



# NASA Science Aircraft Endurance





# Science UAS Development Challenges

- Science missions impose unique requirements on UAS vehicles and operations
  - Access to national/international airspace
  - Unusual flight profiles
  - Reconfigurable sensor installations
  - Cost control
  - Global tele-presence for instrument command and control
- Conducting representative, scientific missions is the best way to push the technology
  - Confirm performance and capabilities
  - Expose limitations and unexpected issues
  - Progressive build-up of mission complexity
  - Engage the science community

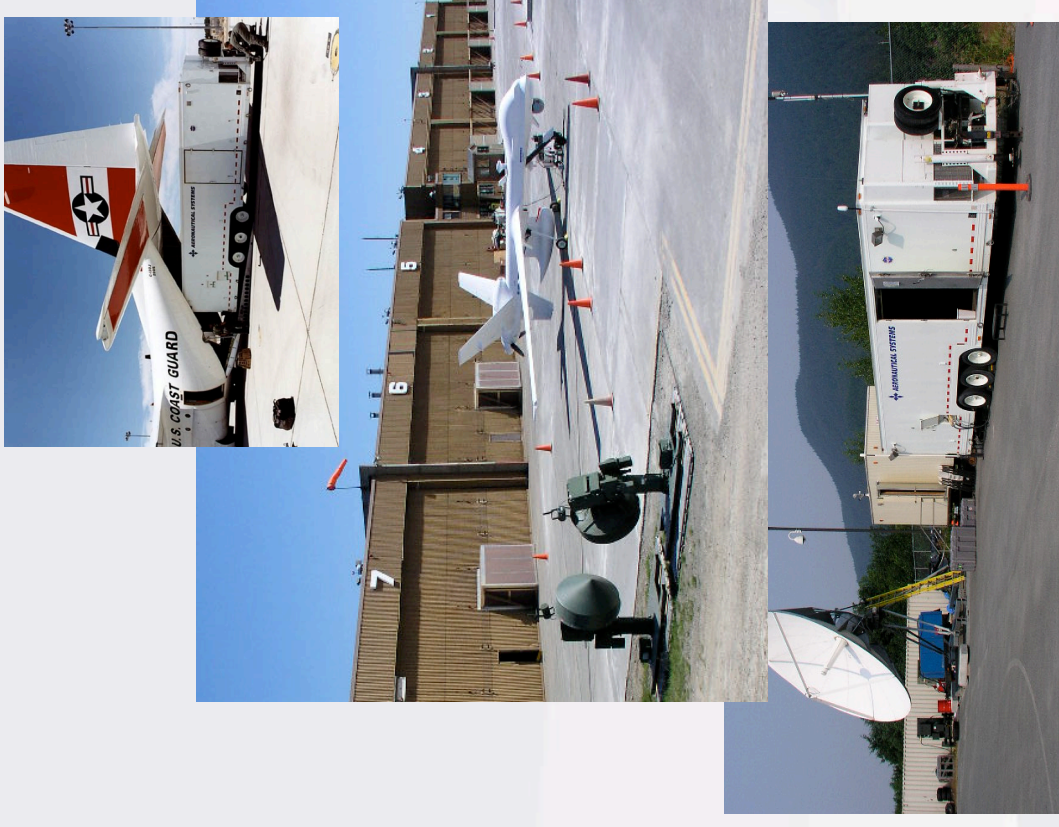
***“ Flight research separates the ‘real from the imagined’  
and makes known the ‘overlooked and unexpected’ ”***

***Hugh L. Dryden***



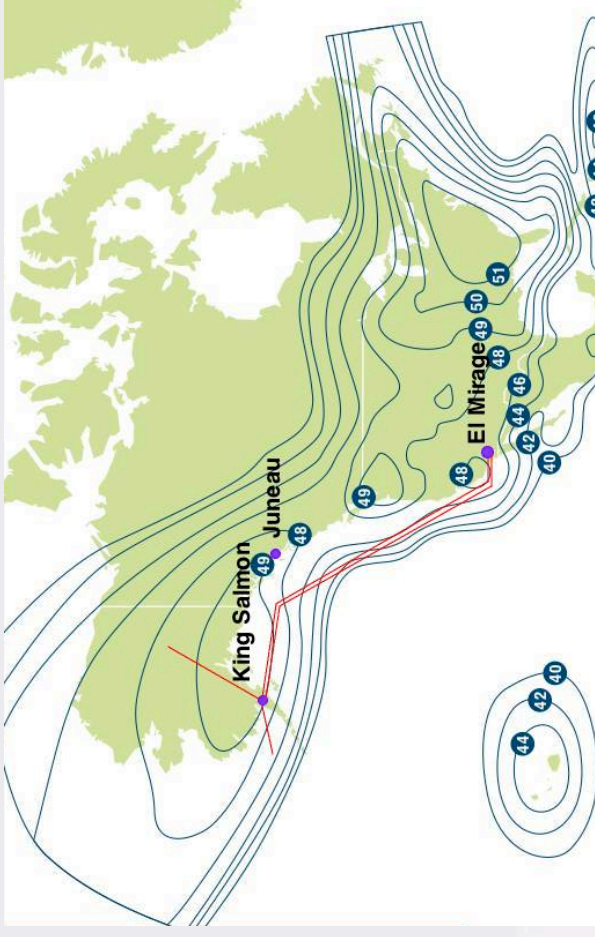
# USCG Alaskan Maritime Surveillance

- Objective: Evaluate use of a UAS for intelligence, surveillance, and reconnaissance (ISR) operations
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- Overview
  - United States Coast Guard (USCG), NASA, GA, and others
  - General Atomics Altair (high-altitude Predator B derivative)
  - Payload
    - ♣ surface surveillance radar, . . .
    - ♣ internal integration
  - Flight Operations: Summer, 2004
    - ♣ Self deployment from California to Alaska
    - ♣ Launch and recovery team operating remote from mission operations center in Juneau
    - ♣ Over the horizon shore to ship communications relay



# USCG Alaskan Maritime Surveillance

- Major Accomplishments
  - Long-range, remote deployment of aircraft, crews, and project team
  - Multiple aircraft control and communication hand-offs
  - Established Northern latitude limit for geostationary satellite data link
  - Provided streaming video to support Alaska wildfire management
- Issues : Reduced Mission Scope
  - Sensor integration complications
  - High latitude satellite coverage less than anticipated
  - Flight limitations due to low satellite elevation angle



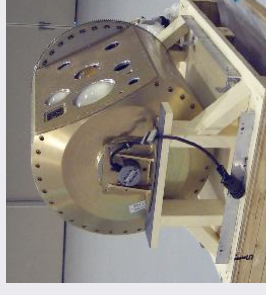


# NOAA/NASA UAV Demonstration Project

- Objective: Evaluate the use of a UAV for future science and operational requirements
  - Atmospheric research
    - ♣ sample low-level Eastern Pacific jets
  - Atmospheric research
    - ♣ coastal mapping, wildlife monitoring, marine enforcement

- Overview

- NOAA, NASA joint project
- General Atomics Altair
- Internal payload integration
- Flight operations
- Spring, 2005 and Fall, 2005
  - ♣ Flights in National Air Space (NAS) under Certificate of Authorization (COA)
  - ♣ primarily at FL430
  - ♣ descents below 18,000 ft escorted by chase plane



Ocean Color &  
Passive Microwave  
Vertical Sounder

Gas Chromatograph  
& Ozone Sensor

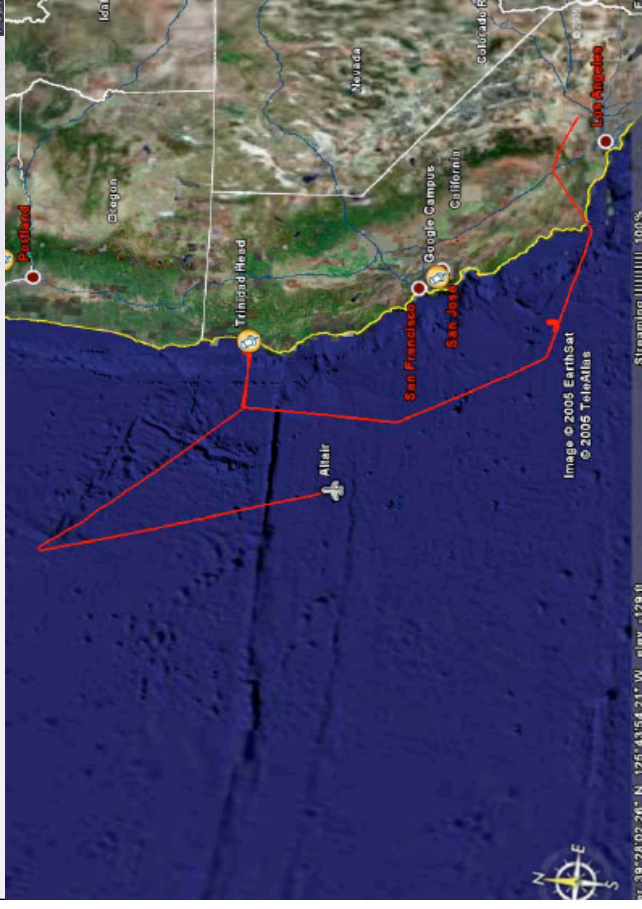
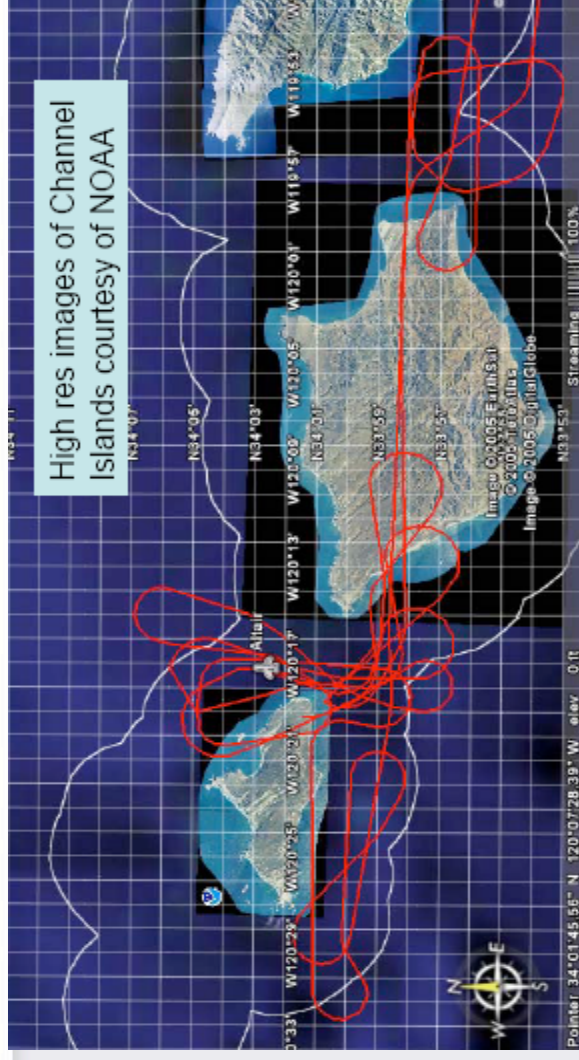


Altair integrated with  
NOAA science payload



# NOAA/NASA UAV Demonstration Project

- Major Accomplishments
  - 20 hour missions
  - over 2500 miles of ocean coverage
  - UAS in the National Airspace with FAA experimental type certificate



- Issues
  - Airspace coordination complications
  - UAS systems reliability under extended high altitude operation
  - Complexity of internal payload integration



# Western States Fire Mission

- Objective: Identify and monitor wildfire events throughout the Western United States and provide near real-time products to field units

- Overview

- NASA, USFS, NOAA, GA partnership
- General Atomics Altair with centerline pod
- Payload

- ♣ Wildfire sensor – Developed at NASA Ames
  - ♣ 13 spectral bands optimized for fire characterization
  - ♣ Fully autonomous
- ♣ near real-time data transfer
  - ♣ on-board processing (geo-rectification)
  - ♣ overlaid with Google-Earth imagery
  - ♣ internet access by end users
- ♣ in-situ atmospheric sampling
- ♣ experiment command and control from ground

- Flight operations: Fall, 2006

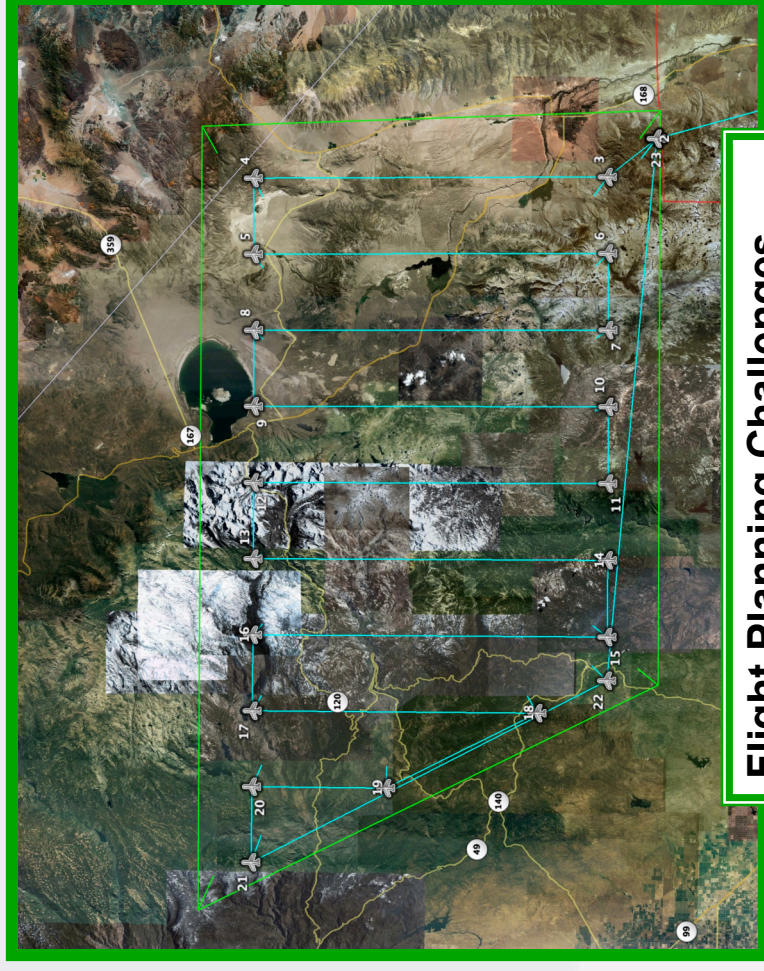
- ♣ **XX flights** from base at Grey Butte, CA; primarily in military airspace
- ♣ Only 1 flight into National Air Space (NAS), always at FL430



# Western States Fire Mission

- Major Accomplishments
  - grid patterns over Yosemite National Park
  - re-direction based on satellite data
  - 23 hour flights
  - coordination with satellite overpasses
  - outstanding data quality
  - demonstrated the importance of virtual presence for experimenters

- Issues: Reduced Mission Scope
  - FAA processes in transition
  - complex risk management issues



## Flight Planning Challenges

- FAA control boundaries
- Special use airspace
- $E_C$  calcs (avoid pop. centers)
- Contingency routing
- Alternate and emerg. landing sites





# Esperanza Fire Emergency Response

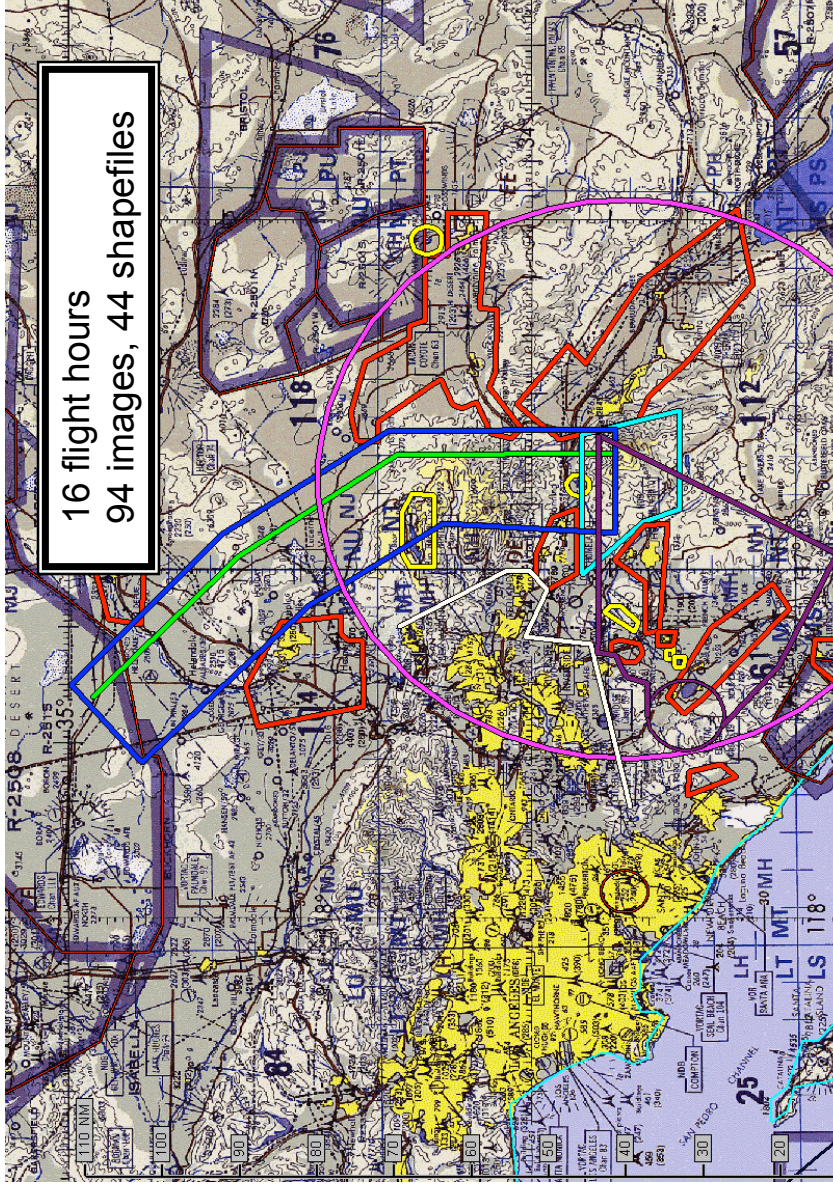
- California Office of Emergency Services requested NASA assistance
  - 40,000 acres (62 sq mi)
  - 5 firefighters killed
  - 34 homes destroyed
- First use of FAA Emergency COA for civilian disaster response





# Esperanza Fire Emergency Response

- Friday, Oct. 27 10:00 AM - Received request
- Saturday at 3:45 PM – Aircraft launched
  - FIRE sensor returned to Grey Butte and installed on A/C
  - Ground safety analyses
  - Requested and received FAA approval
  - Aircraft prepared for flight
- Sunday 7:30 AM - Landing

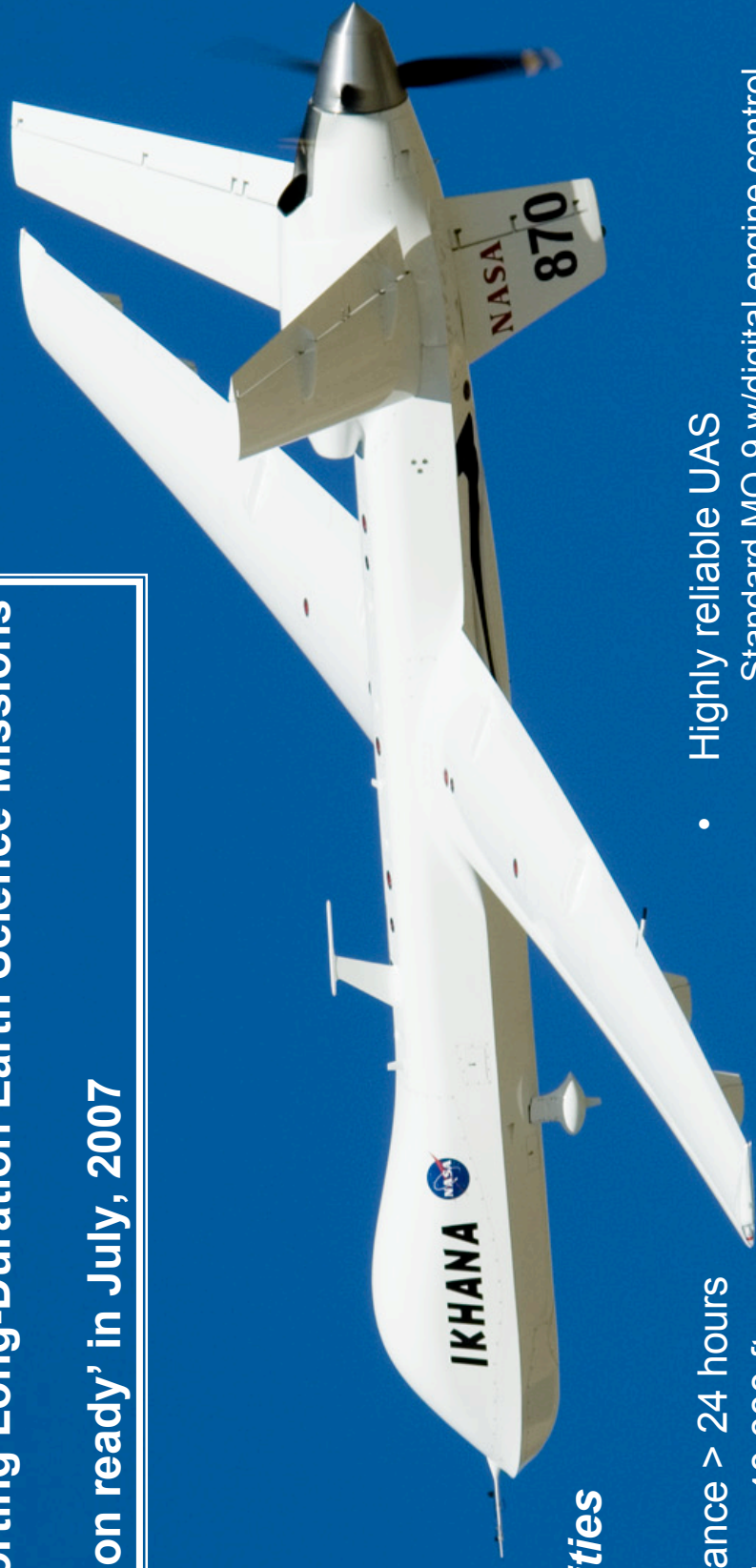




# Ikhana (Predator B)

A NASA Unmanned Aerial System  
Supporting Long-Duration Earth Science Missions

‘Mission ready’ in July, 2007

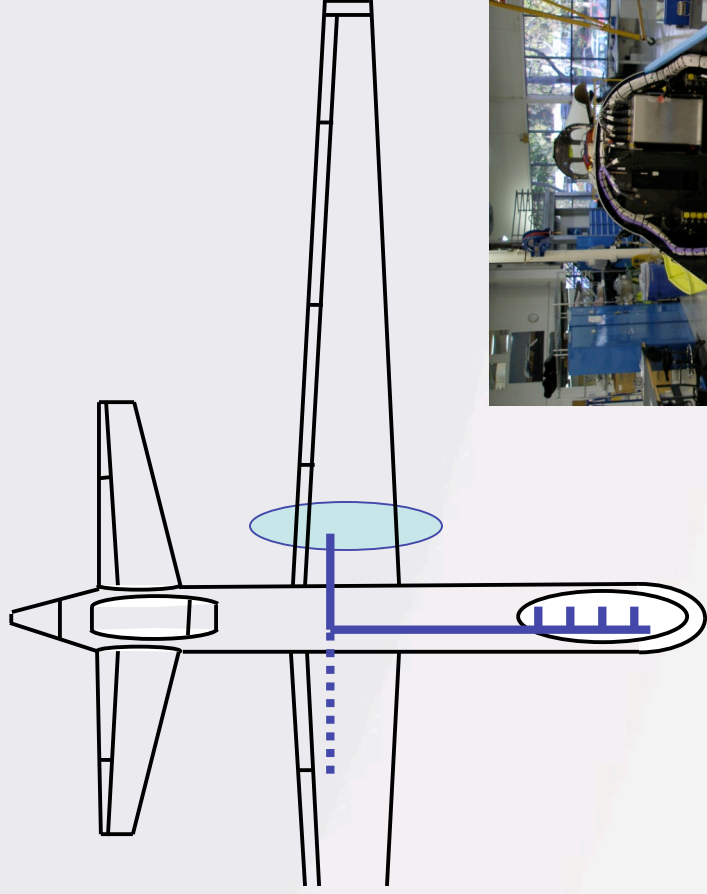


## Capabilities

- Endurance > 24 hours
- Altitude > 40,000 ft
- Payload > 2,000 lbs (750 in pod)
- Range 3,500 nautical miles
- Highly reliable UAS
  - Standard MQ-9 w/digital engine control
  - Triple redundant flight control systems, dual redundant power & networks
  - Predator family has logged over 200,000 hours



# Ikhana (Predator B)

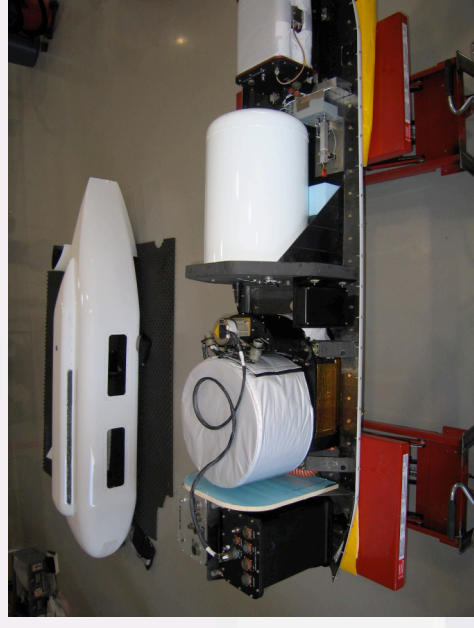


## Payload Areas

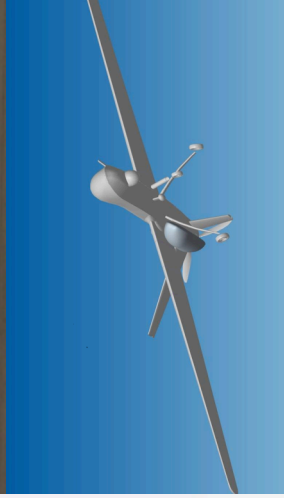
- Wing-mounted pods
- Avionics Bay
  - Payload Tray
  - Chin compartment

## Experimenter Network

- Ethernet network connecting avionics bay and remote pods
- Communications, recording, downlink, time code, aircraft state data



# Ikhana (Predator B)

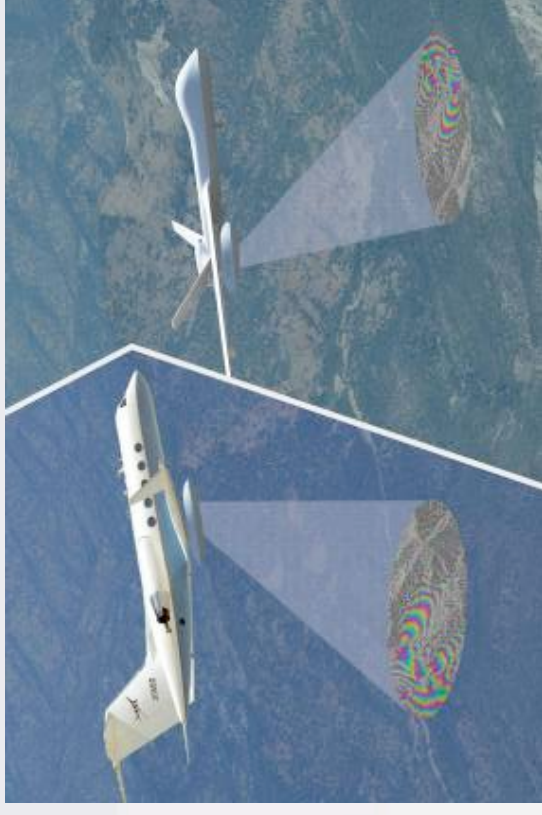


## ***Other Mission Support Features***

- Experimenter network and data system
- Mobile ground control station
  - Ku Satcom for over the horizon missions
  - 6 experiment monitoring stations
- Airborne Research Test System
  - 3 processor research flight control and/or mission computer
  - allows autonomous control of the aircraft and some systems
  - able to host research control laws

# UAV Synthetic Aperture Radar (UAVSAR)

- Objective: Advanced airborne SAR capability
  - autonomous operation
  - interferometry products
- Radar development - NASA JPL
- Aircraft modifications and flight testing – NASA Dryden
  - Development activity on G-3
  - Instrument housed in external pod
  - A/C precision navigation for
    - ♣ repeat pass interferometry
    - ♣ flight path control to within +/- 5 m
- Portable to Predator B class UAS
  - long duration for continuous event monitoring
  - high altitude for long uninterrupted flight lines





# Global Hawk

## **Capabilities**

- Endurance > 30 hours
- Altitude 65,000 ft
- Payload > 1,500 lbs
- Highly reliable, mature UAS

## **Mission Support Features**

- Multiple payload locations
  - 40 ft<sup>3</sup> pressurized
  - 62 ft<sup>3</sup> un-pressurized
  - Can accommodate wing pods (future)
- Flies above conventional air traffic
- Fully autonomous control system, take-off to landing



# Related Technologies

- Sub-orbital Tele-presence (Airborne Sensor Web)
  - Develop/demonstrate low-cost services for science payloads
    - ♣ Situational awareness
    - ♣ Decision support; productivity
    - ♣ Sensor web: *i.e.* Instrument interaction/C4I
  - Applicable to all suborbital platforms, but special significance for UAS
- Access to airspace
  - Near-term expectations (next five years or so)
    - ♣ Certificate of Authorization processes
  - Long-term
    - ♣ Rules and procedures for UAS certification and routine operation in the national air space
    - ♣ Technology development





# Summary

- Unmanned Aerial Systems offer great potential for Earth science missions of the future
- Performing representative science missions has been critical to understanding and guiding UAS technology implementation
- New platform and sensor capabilities are under development
- A follow-on to the Western States Fire Mission will be conducted in Summer, 2007 with the NASA Ikhana aircraft

